

# Manchester encoding using RS232 for Microchip PIC RF applications

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## Introduction

The following takes a look at transporting Manchester encoded data [2] using RS232, over a radio frequency (RF) link [5].

Those familiar with RS232 / RS485 etc will be aware that when data is sent through a cable to remote equipment it gets there with good reliability. If error detection is required, this can take the form of a checksum as part of a packet-based protocol. However, should you want to send the same data over an RF link a number of things have to be taken into consideration. Most notably is the need to maintain a zero DC component in the serial bit stream.

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## Manchester encoding

Manchester encoding (also known as Biphase Code) is a synchronous clock encoding technique used to encode the clock and data of a synchronous bit stream. In this technique, the actual binary data to be transmitted over the cable or RF link are not sent as a sequence of logic 1's and 0's as in RS232 (known technically as Non Return to Zero (NRZ)). Instead, the bits are translated into a slightly different format that has a number of advantages over using straight binary encoding (ie NRZ).

The main advantages of using Manchester encoding in PIC wireless applications are:

1. Serial bit stream has a DC component of zero
2. Error detection is simple to implement
3. Can be encoded using RS232 software/hardware
4. Simple to implement on target device (Microchip PIC [3])

In general, when transmitting serial data to a radio receiver, a DC component of zero must be maintained (over a finite time). This is so the demodulator in the receiver can properly interpret the received data as 1's and 0's. Manchester encoding allows us to do this.

Manchester encoding follows the rules:

1. If the original data is a Logic 0, the Manchester code is: 0 to 1 (upward transition at bit centre)
2. If the original data is a Logic 1, the Manchester code is: 1 to 0 (downward transition at bit centre)

It can be seen that there are two bits of Manchester encoded data for each bit of original data. The penalty for doing this is Manchester encoded data consumes more bandwidth than NRZ encoding.

Example of Manchester Encoding:

The pattern of bits "0 1 1 1 0 0 1 " encodes to " 01 10 10 10 10 01 01 10" (least significant bit (lsb) is left most).

Alternatively this can be represented as two 4-bit nibbles

1. The pattern of bits "0 1 1 1 " encodes to " 01 10 10 10 "
2. The pattern of bits " 1 0 0 1 " encodes to " 10 01 01 10 "

This step leads us to sending 8-bits of data as two RS232 bytes.

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## Illegal codes

Given that a 0 encodes to 01 and 1 encodes to 10, it follows that 00 and 11 are illegal sequences or codes. These codes are used to error check the data.

It is possible to have the 4-bit illegal code " 00 00 11 11 ", which is an unlikely occurrence. The 'illegal code' has the property of having a DC component of zero and has one, 0 to 1 transition.

We can use this 'illegal code' (" 00 00 11 11") as a unique start/stop pattern to identify the boundaries of our Manchester encoded bit stream or data frame.

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### RS232 carries Manchester encoding

We can use RS232 as a carrier for Manchester encoding provided that bytes of RS232 are transmitted end-to-end. RS232 has a start bit, logical 0, and a stop bit, logical 1 which have a DC component of zero. In our real life application 2-stop bits are used by the CCS [1] RS232 built in function. What 2-stop bits means is that the DC component is no longer zero, so here we make a compromise and say the DC component is near zero (ie the extra stop bit has a 1/10 effect on the DC component).

### RS232 bit stream

The following represents two bytes of RS232 end-to-end bit stream in the format 8-data bits, 2-stop bits: ...MMMMMMMSDDDDDDDDPPSDDDDDDDDPPMMMMMM...

Where:

M is line idle (logic 1)  
S is start bit (logic 0)  
D is data bit  
P is stop bit (logic 1)

All that's required is to insert Manchester encoded data into the RS232 data bits. There are 4 Manchester encoded bits in each RS232 byte.

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### Application

In this application it is assumed the 'C' functions [1] `putc()` and `getc()` directly output or input TTL levels from a radio transmitter or receiver respectively.

#### Start data frame

The data frame is started by transmitting a preamble of start/stop patterns (SS) to the radio receiver. The number of SS patterns depends on the characteristics of the radio receiver. In general, enough SS patterns are needed to:

1. Initialise the receiver demodulator
2. Allow the RS232 decoder to synchronise to the start bits of each RS232 byte
3. Indicate to the software communications (comms) handler that an SS pattern has been received and data is expected to follow.

\* An additional stop bit is inserted at the end of each SS pattern to allow the RS232 decoder to 'catch up' with the start bit.

The unique SS pattern " 00001111 " (lsb left most) is equivalent to the hex code 0xF0 (lsb right most). The following 'C' statements will send a preamble of three SS patterns.

```
putc(0xF0);  
delay_us(500); // *  
putc(0xF0);  
delay_us(500); // *  
putc(0xF0);  
delay_us(500); // *  
putc(0xF0);  
delay_us(500); // *
```

\* Additional 500us stop bit based on a bit rate of 2000 bits per second (kps).

The received stream will look something like:

...00000000**00001111****1110**0000**1111****1110**0000**1111****1110**0000**1111****1111**

Note: In this example the receiver has an idle state of 0. This serves a useful purpose in that the software driven `getc()` routine will interpret this as a start bit

and proceed to receive data, which avoids waiting for data if the line idle state is a 1. Interestingly, kbhit() does not provide a good solution if the line idle state were a 1, since noise, which is prevalent when no signal is present, can trick kbhit() into thinking there is a start bit when in fact there is none to be detected by the following getch(), and a hang may ensue.

### Send data

Let's for example send the data byte 0x41. This is encoded into two Manchester encoded RS232 bytes. The least significant nibble is transmitted first:

Working out long hand:

1. 0x41 represented as a bit stream is " 1000 0010 "
2. Lower nibble " 1000 " Manchester encodes to: " 10 0101 01 " (i.e. 0xA9)
3. Upper nibble " 0010 " Manchester encodes to: " 0101 10 01 " (i.e. 0x9A)

The following 'C' statements will transmit the Manchester encoded byte 0x41:

```
putc(0xA9); // lower nibble
putc(0x9A); // upper nibble
```

In real life this would be carried out by the routine below:

```
void SEND_DATA(BYTE txbyte)
{
    int i,j,b,me;

    b = txbyte;

    for (i=0; i<2; i++) {
        me = 0;          // manchester encoded txbyte
        for (j=0 ; j<4; j++) {
            me >>=2;
            if (bit_test(b,0) )
                me |= 0b01000000; // 1->0
            else
                me |= 0b10000000; // 0->1
            b >>=1;
        }
        putc(me);
    }
}
```

More data can be sent if required.

### End data frame

To end a data frame 0xF0 is transmitted:

```
putc(0xF0);
```

It could be argued that this is not necessary since the preamble in the next data frame will reset the comms handler. However the comms handler can use it as an indicator that the data frame is complete.

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### Decoding data

Converting Manchester encoded data back to original data is straight forward and error checking may be carried out at the same time. Since data arrives as 4 pairs of Manchester encoded data a simple shift and test algorithm can be implemented to retrieve the original data.

The routine below decodes four bit-pairs to one nibble of original data:

```
BYTE DECODE_DATA(BYTE encoded)
{
    BYTE i,dec,enc,pattern;
```

```

enc = encoded;

if (enc == 0xf0)      // start/end condition encountered
    return 0xf0;

dec = 0;
for (i=0; i<4; i++) {
    dec >>=1;
    pattern = enc & 0b11;
    if (pattern == 0b01)      // 1
        bit_set(dec,3);
    else if (pattern == 0b10)
        bit_clear(dec,3);    // 0
    else
        return 0xff;         // illegal code
    enc >>=2;
}
return dec;
}

```

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### Other considerations

When software generated RS232 is used for receiving serial data, it is important that the latency between the start bit and the execution of `getc()` is kept to a minimum. This is not an issue if `getc()` is waiting for serial data, but becomes important when `kbhit()` is used to determine the presence of a start bit. Typically `kbhit()` is used in a tight loop (see below). The latency is the time round the loop.

```

while(1) {
    if ( kbhit() )
        data = getc();
    ...
    some other code executed here
    ...
}

```

For example if the bit rate is 2000bps, one bit time is therefore 500us. A latency of no more than 50us is suggested [4]. Higher bit rates require less latency.

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### Conclusion

Manchester encoding is suitable for bit streams in radio communications and can be transported using standard RS232 functions. It is simple to encode, decode and has good error detection negating the need for 'check-summed' data. Manchester encoding is practical and easy to implement on Microchip PIC devices.

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### References

- [1] "C Compiler Manual", Custom Computer Services Inc, [www.ccsinfo.com](http://www.ccsinfo.com)
- [2] "Manchester Encoding" Gorrry Fairhurst, [www.erg.abdn.ac.uk/users/gorrry/course/phy-pages/man.html](http://www.erg.abdn.ac.uk/users/gorrry/course/phy-pages/man.html)
- [3] Microchip PIC [www.microchip.com](http://www.microchip.com)
- [4] "How do I get `getc()` to timeout after a specified time?", [www.ccsinfo.com/faq](http://www.ccsinfo.com/faq)
- [5] "AM RF Transponder", [www.quickbuilder.co.uk/qb/libs/comms.htm#amx](http://www.quickbuilder.co.uk/qb/libs/comms.htm#amx)